MC5000 Series Medium Programmable Logic Controller

MEGMEET

Shenzhen Megmeet Control Technology Co., Ltd

Add:5F, Ziguang Information Harbor, Langshan Rd., Science& Technology Park, Nanshan District, Shenzhen, China

Tel: +86-755-86600500

Fax: +86-755-86600748

Zip: 518057

Website: www.megmeet.com

Hotline: 400-666-2163



Megmeet reserves the right of final interpretation of the technical parameters of this manual.









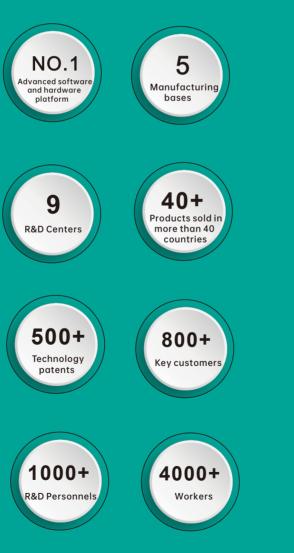
MEGMEET's Qualities Are Shared All over the World

The World Benefits from MEGMEET

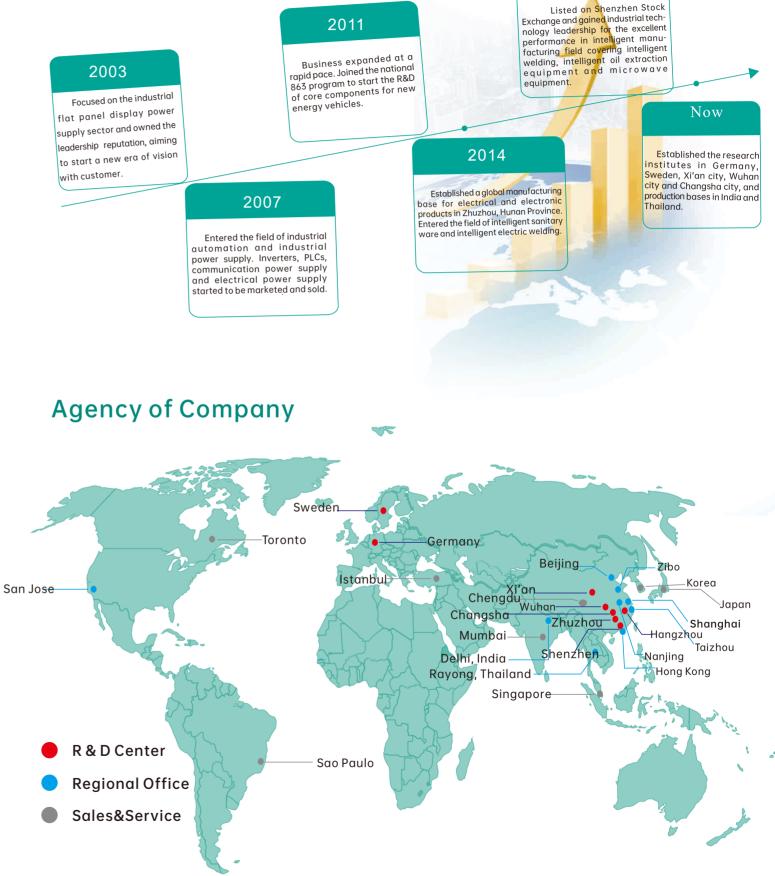
Megmeet (Stock Code:002851), founded in 2003 with a registered capital of 313 million yuan, is one of the first national-level high-tech enterprises centered on power electronics and industrial control technology. With the vision of becoming a world-class solution provider in the field of electrical control and energy conservation, our company aspires to be Megmeet Everywhere.

Company's business includes smart home appliances, industrial automation, rail transit, new energy vehicles, clean energy and other fields. Our products are widely used in engineering machinery, 3C electronics, machine tools, plastics, non-standard equipment, rail transportation, medical, communications, IT, electric power, photovoltaic, oilfields, police equipment, industrial welding machine, industrial microwave, inverter air conditioner, frequency microwave, flat panel display, outdoor color screen, intelligent sanitary ware and other industries. There are good markets for these products in Europe, America, India, Brazil, South Korea, Japan and other more than 40 countries, and own trust from over 800 customers.

Since its establishment, our company has made rapid development with the pragmatic and innovative vision, relying on talents and technological advantages which embodies more than 1000 R&D engineers and 500 technology patents. Now, we establish a industry-leading software and hardware platform for product R&D, testing and manufacturing.



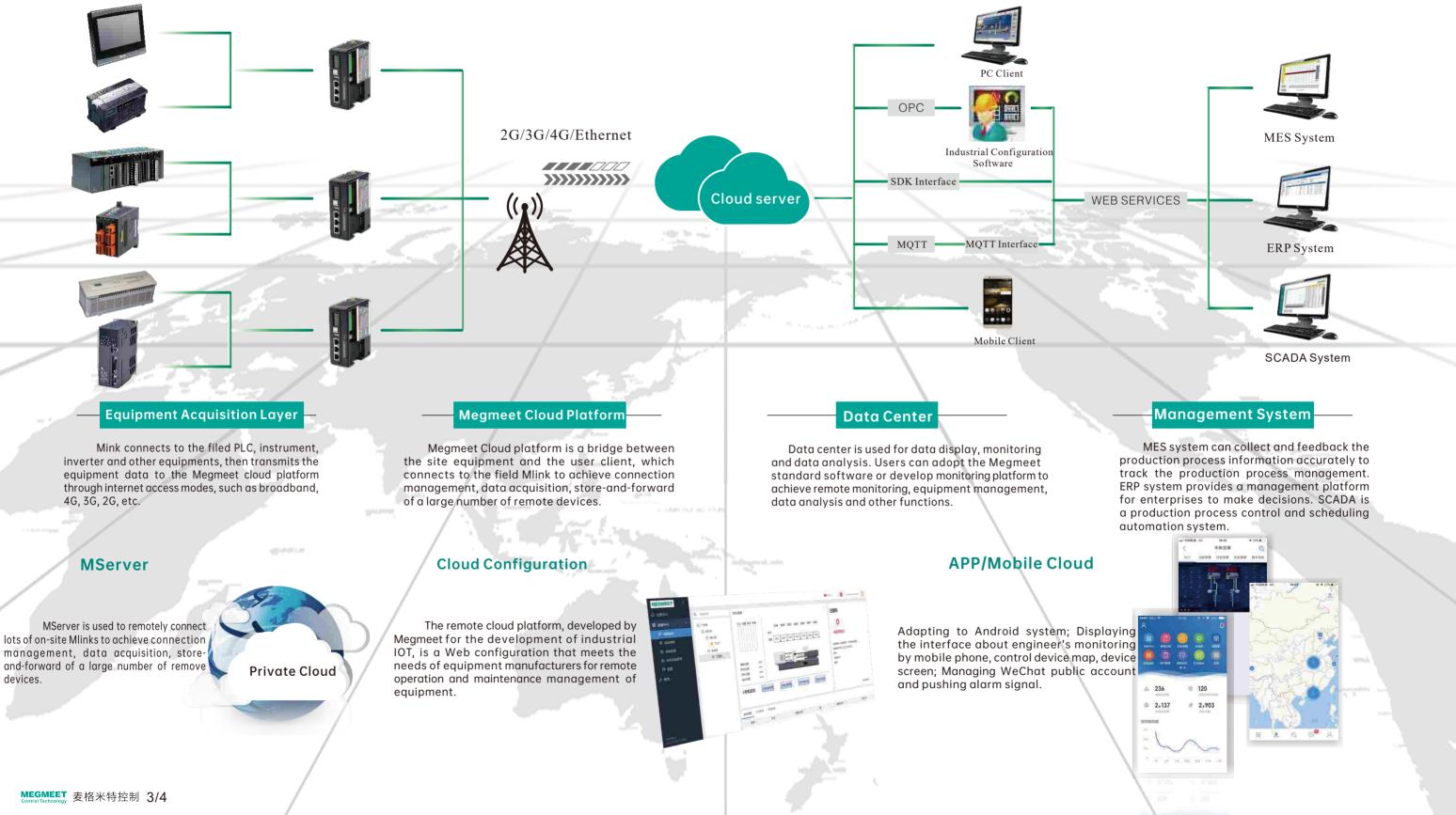
Development Course

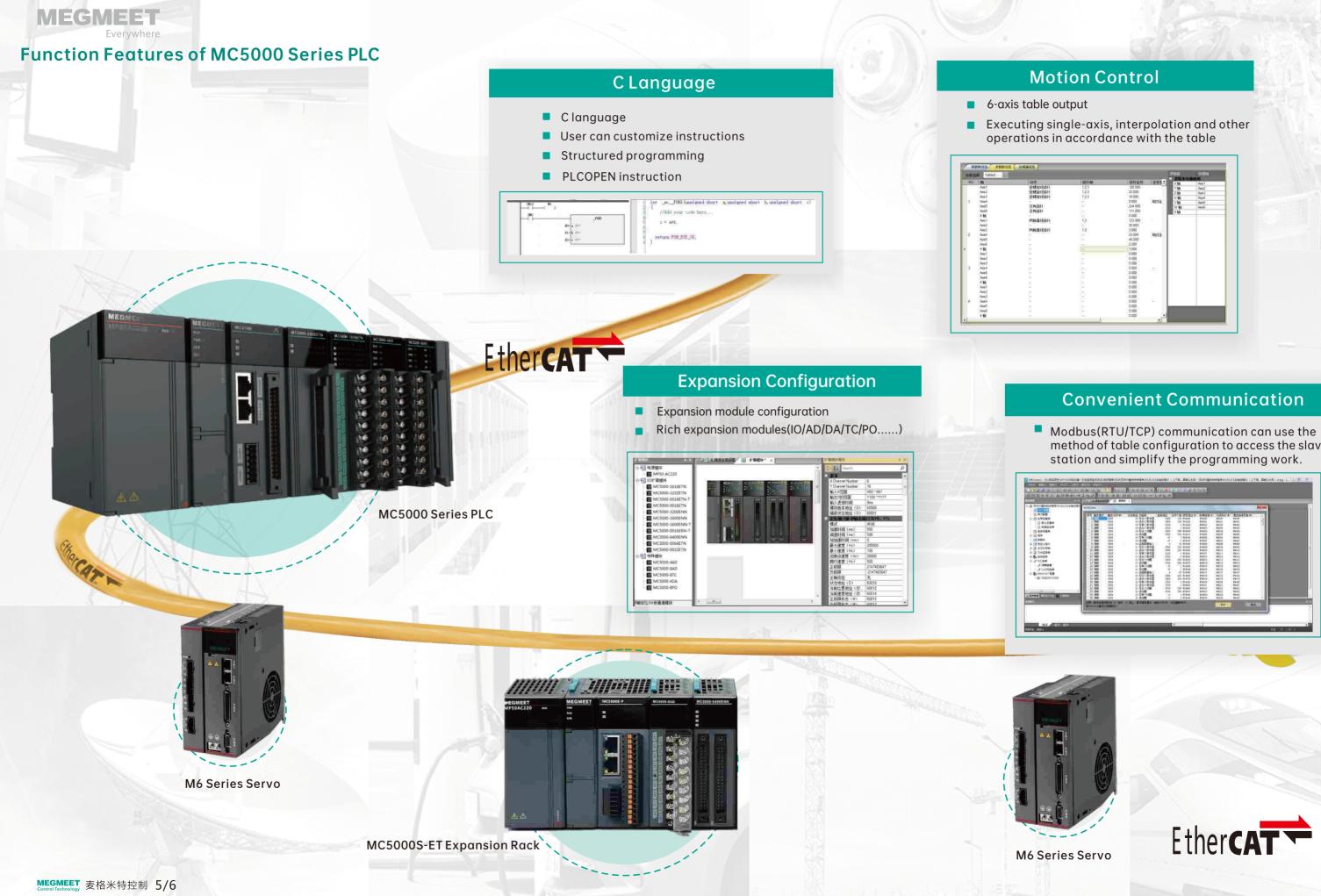


2017



Industrial IOT Solutions





method of table configuration to access the slave

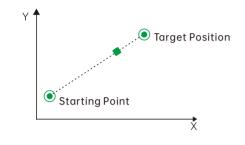
	1	11 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	• 3							
ACCOUNT OF THE OWNER OF	MUDDPHC	-	_			_	_	_	100.000	
	TO NTEE		LINEL THEIL	America 7	17- A 20-01-4-	AREAS-ST.	1300 m	Aum att Mar.		
	A DOMESTIC AND DOMESTIC	CERT	10 读造小数拆满	100	120 mar.29	ET ALCO	#1311	11111	10	
	2 820	ants .	10 元单/ 長市課	2374	1.204240	EDBKG7	#4722	#+#22.	2	
	5,84	100	10 成長り 営井時 11 第4日 11日	2118	1.304042	metta -	#4033	使中枢处		
	1.1.25	ani -	11 49 1400	2006	22. E400	BTROOM -	#1014	weeks.		
	22.00	10000	川石東小社田	10	1 1000	FU8000		444		
	1.84	COLT.	10 121-100		1.014040	anaber -	9400	184407		
	+ F2E	0338	11 法把回算解入	1.00	(E. BUATE)	87140000	04004	HEADE.		
	(# ##D	011	() 当由小市中福	1004	120 #14300	874225	#1019	dents		
	11,200	0000 0020	11 23- EVE	2016	130 154400	phasso .	#87(i) #5711	dea11		
	17 428	0001	11 251 298	2110	1 21 43 47	manta -	84212	194412		
	12 600	1111	54160	anie	into science	BURDY'S	#1210	W6517		
	14.335	1222	D GUN	3706-	28 8455	\$22134	1042114	MARIN		
	16 200	0221	11 当第143篇	16	3,800,80	\$5901F	#此(5)	044625		
	1 MR	CUT	11 第2日間 11 日本町 日本3	10	1 10 643	ETRATE	#42(4) #42(7)	ST4550		
	1 400	CLER	11 年後の日本	2000	121 214231	EDD15	WAC11	#**11		
100	1.200	1000	1 44 852	1000	Lat Matte	ETELLS .	8411	diate.		
	12,100	CTTT .	11 加速小型分離	2110	1.014040	BT18000	P401	P1521		
	-21, 620	100	11 決定(単物語)	Lite	100041	FUELD	winit :			
	12 820	1221	14 特征小线圈	1013.0	20 81400	Marriel .	**=	944=		
	1.2 2	013	11 SZ(K)10 11 11 10 - 1 (1) 10	- (1114)	1 104000	100	#4522	04422		
£	12.22	COLO I	1 218		1 martes	ENG.	water.	#167		
			IS NO. BOMONIC, N	1.17.1		Press .				
		Departure and and a					- 215	80		



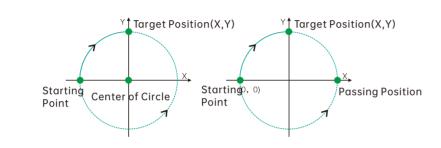
Powerful Motion Control Function

Supported Function: 64 axis bus control, 6 axis differential pulse, linear interpolation, circular interpolation, electronic gear and electronic CAM.

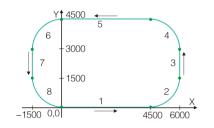
Linear Interpolation(LIN)



Circular Interpolation(CW/CCW)



Combination of LIN and CW/CCW



Speed of Interpolation

The speed of interpolation motions in any two axis can be up to 200KHz.

The direction of the tool is kept perpendicular to the trajectory during

Normal and Tangent Interpolation

the control of circular interpolation.

Three-dimensional Helical Interpolation

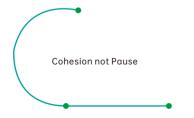
Achieving three-dimensional helical interpolation operation

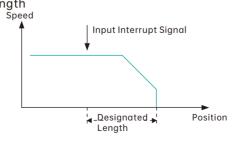


Continuous Interpolation

Interrupt Set Length

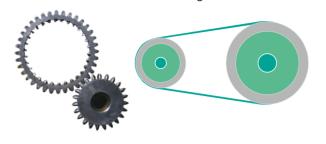
Detecting the specified input and then running according to The speed can be kept during the switch of the set length interpolation in multistage continuous interpolation. Speed





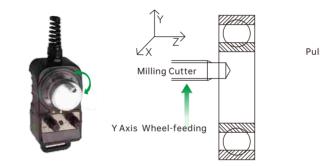
Starting Point

Advanced Electronic Gear Algorithm(GEARBOX) Electronic CAM Function Controlling the slave axis to move along with the master axis at a certain electronic gear ratio.



Hand Wheel

Being suitable for occasions where manual positioning is required, and the variable pulse output can be set to achieve the manual accurate positioning during parts processing.



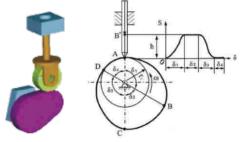
Supporting CAD diagram import and Simple G code function

 Supporting 16 instructions, include single axis positioning, linear interpolation, circular interpolation, jump, cycle, etc.

- Maximum control of 8 axis whose parameters and motion parameters can be configured.
- Supporting up to 4 independent processing tables
- Supporting teaching, manual input, importing CAD graphics to generate the processing program
- Interacting data with PLC conveniently and efficiently

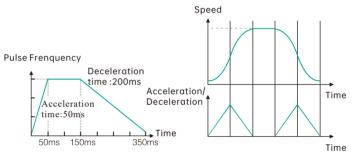


Holding four groups of 2048 CAM data curve, the slave axis moves along with the master axis and keeps pace with the speed of the master axis.



Asymmetric Trapezoidal Acceleration/Deceleration and S-curve Acceleration/Deceleration

Supporting for the asymmetric trapezoidal acceleration/ deceleration and S-curve acceleration/deceleration function.



Clanguage

Standard C language, supports standard language library function

- Users can customize instructions to implement the core algorithm of device
- User-defined instructions can be encapsulated, encrypted, import and export

Suni = 0.0; //累计积分值多周期要保留,所以必须全 FredD = 0.0; //撕次散分值多周期要保留,所以必须金 Yout = 0.0; //当前控制脑出值 mc_PID(float PV,float SV,float Kp,float Ki,floa		loat Lini	lt, float 🕫	Out, unsigned char *Alarm)
(Add your code here coat e = 0.0; / 代盤備発 coat 物 = 0.0; /代投初頃 coat 初 = 0.0; /代投功項 coat 7 (1 = 0.0; /代投功項				
cost Verr = 0.0; //计算输出误差调节 cost Helerm = 0; //报警输出		(*FIDIQ#):	比例、微分、	积分项计算
= SY - PV :] mI = e + SumI;	307703600 19	58212 		
. = Sumī + Ki; = (e - PovdD)+Ed;				163-79 ← Dat → -864 系統反策 160-59 ← Alara → -160
ut = Vout + Verr; //本次输出 = 上一次值 + 偏差调节 Ⅴ				
Yout = Limit:				Di−IZi ← #99Ki
l = (e - FwdD)+Ed; xx = Vp+V1+Vd; xt = Vout + Vexr; //本次输出 = 上一次值 + 偏差调节 V ?(Vout>=Limit)		1,8799		系統反対 100-57 (- Alexa -) 現在 120-20 (- 出門) 10-21 (-

MEGMEET Everywhere

MC5000 Series Medium Programmable Logic Controller

MC5000 is a perfect combination of motion control and medium PLC controller, supporting EtherCAT multi-axis bus control, motion controls including interpolation, CAM, G code, and supporting C language programming and other powerful functions. MC5000 is suitable for the industries of lithium battery, 3C electronics, photovoltaic, municipal, textile, printing and packaging, HVAC, non-standard equipment, etc.



Features:

Powerful Motion Control: Motion control is handled by a separate CPU Based on EtherCAT bus control: control cycle 250us, up to 64 axis control

Based on pulse output: 2M differential pulse, 100K collector plate, 8PO expansion, up to 38 axis pulse control

Operation Speed: adopting the multi-core processing method to perform communication control, operation and logic, motion control, and the 100K-step standard procedure executes no more than 2.2ms

- C Language: supporting standard C programming, 2400dmips
- Rich interface: Ethernet, RS485, USB, SD card
- Large Capacity: program capacity 320K steps, C language 2M Byte, data capacity 2M Byte

Naming Rules for Product Modules



Specification of Main Module

	Model	MC5200E	MC5101EB	MC5100EA	MC5000EA64	MC5000E64	MC5001EB64		
Item		Universal Controller	Pulse Motio	on Controller		Bus Motion Controller	•		
Number of Lo	ocal Expansion Module			16 (Maximum 1	1024 points)				
Program Capacity	Ladder Diagram	320K Step							
rogram capacity	User C Language			2M	byte				
D	ata Capacity	2M Byte							
Speed of Instruction	Ladder Diagram	2ms/100K Step							
Execution	C Language			2400	dMIPS				
Spee	d of Bus Refresh			16 IO Module 0.	1ms (No scan time)				
Ρι	ulse Output	-	4 axis (collector)	6 axis(diff	erence)	-	4 axis (collector)		
Hig	h-speed Output	_	2 groups AB phase input	1 group 5V difference + 2	groups AB phase input	-	2 groups AB phase input		
Gene	eral IO (transistor)	16 input, 16 output	4 input, 4 output	4 input, 4 output 16 input, 16 output 4 ir		4 input, 4 output			
Number o	Number of Positioning Module 4 MC5000-8PO expansion module								
	Number of Motion Axis	- 64(Maximum)							
EtherCAT	Number of Bus Expansion Rack		8 groups MC5000S-ET						
	Min. Synchronization Time	250us							
	Ethernet (Socket)			7 (ModbusTCP master	/slave,free protocol)	protocol)			
Communication	RS485		2 0	channels (Modbus maste	er/slave, MCbus, free pi	rotocol)			
	Standard C Language			Supporting sta	ndard C language				
C I and a second	Operation Mode	C language operates programming mixed with ladder diagram/ Independent programming							
C Language	Function Library			Providing rich star	ndard function library				
	User-defined Library		Supporting to enca	psulate function blocks	with C language (impo	rt, export, encryption)			
	CAM and Interpolation	-	3 groups CAM/1 group n	nulti-axis interpolation		Yes			
Motion Control	Table Output	_			10000 steps × 2 group	IS			
	CAD File Import	-			Yes				
Hardware	SD Card			Y	es				
Resources	USB Download			Y	es				

Series Modules

Model	Module Descript CPU Module		Specification			
	IO of Main Module	Number of bus control axis				
MC5200E	Input: 16 channels Output: 16 channels transistor	-	Standard medium module Terminal: cluster terminal			
MC5100EA	Input: 4 channels 200K pulse, 3 channels 1M differential pulse Output: 4 channels transistor, 6 groups 2M differential pulse	_	Pulse main module			
MC5101EB	Input:8 channels (support 4 channels 200K pulse)	-	Terminal: cluster terminal Pulse main module			
MC5000E8	Output:8 channels transistor (support 4 channels 200K pulse) Input: 16 channels		Terminal: Euroblock Bus main module			
	Output: 16 channels transistor Input: 16 channels	8 axis EtherCAT	Terminal: cluster terminal			
MC5000E16	Output: 16 channels transistor	16 axis EtherCAT	Bus main module Terminal: cluster terminal			
MC5000E32	Input: 16 channels Output: 16 channels transistor	32 axis EtherCAT	Bus main module Terminal: cluster terminal			
MC5000E64	Input: 16 channels Output: 16 channels transistor	64 axis EtherCAT	Bus main module Terminal: cluster terminal			
MC5001EB8	Input:8 channels (support 4 channels 200K pulse) Output:8 channels transistor (support 4 channels 200K pulse)	8 axis EtherCAT	Bus main module Terminal: Euroblock			
MC5001EB16	Input:8 channels (support 4 channels 200K pulse) Output:8 channels transistor (support 4 channels 200K pulse)	16 axis EtherCAT	Bus main module Terminal: Euroblock			
MC5001EB32	Input:8 channels (support 4 channels 200K pulse) Output:8 channels transistor (support 4 channels 200K pulse)	32 axis EtherCAT	Bus main module Terminal: Euroblock			
MC5001EB64	Input:8 channels (support 4 channels 200K pulse) Output:8 channels transistor (support 4 channels 200K pulse)	64 axis EtherCAT	Bus main module Terminal: Euroblock			
MC5000EA8	Input:4 channels 200K pulse, 3 channels 1M differential pulse Output:4 channels transistor, 6 groups 2M differential pulse	8 axis EtherCAT	Bus main module Terminal: Europiock			
MC5000EA16	Input:4 channels 200K pulse, 3 channels 1M differential pulse	16 axis EtherCAT	Bus main module			
	Output:4 channels transistor, 6 groups 2M differential pulse Input:4 channels 200K pulse, 3 channels 1M differential pulse		Terminal: cluster terminal Bus main module			
MC5000EA32	Output:4 channels transistor, 6 groups 2M differential pulse Input:4 channels 200K pulse, 3 channels 1M differential pulse	32 axis EtherCAT	Terminal: cluster terminal Bus main module			
MC5000EA64	Output:4 channels transistor, 6 groups 2M differential pulse	64 axis EtherCAT	Terminal: cluster terminal			
MREAACOOO	Power Mo	dule				
MP50AC220	Input: 100~240Vac, Output: 24V/2A	Madula	AC power module			
MC5000-3232ETN	IO Expansion	Module	Cluster terminal			
		32-point 24DVC input/ 32-point transistor output				
MC5000-1616ETN	16-point 24DVC input/16-point transistor output		Cluster terminal			
MC5000-3200ENN	32-point 24DVC input					
MC5000-0032ETN	32-point transistor output					
MC5000-6400ENN	64-point 24DVC input	64-point 24DVC input				
MC5000-0064ETN	64-point transistor output	Plug and pull screw terminal				
MC5000-1600ENN-T	16-point 24DVC input	16-point 24DVC input				
MC5000-0016ERN-T	16-point relay output		Plug and pull screw terminal			
MC5000-0016ETN-T	16-point transistor output		Euroblock			
MC5000-3200ENN-P	32-point IO input		Euroblock			
MC5000-0032ETN-P	32-point IO output		Euroblock			
MC5000-1616ETN-P	16-point 24DVC input/ 16-point transistor output (with 4	channels high-speed counter)	Euroblock			
MC5000-1600ENN-P	16-point IO input		Euroblock			
MC5000-0016ETN-P	16-point IO output		Euroblock			
MC5000-0016ERN-P	16-point relay output		Euroblock			
	Analog Quantity	Module				
MC5000-8AD	8-channel analog quantity input module		Plug and pull screw terminal			
MC5000-4AD	4-channel analog quantity input module		Plug and pull screw terminal			
MC5000-4DA	4-channel analog quantity output module		Plug and pull screw terminal			
MC5000-4PT	4-channel thermal resistance temperature module		Plug and pull screw terminal			
MC5000-8TC	8-channel thermocouple temperature module		Plug and pull screw terminal			
MC5000-4TC	4-channel thermocouple temperature module					
1100000-410	4-channel thermocouple temperature module Motion Control Mo	dule	Plug and pull screw terminal			
MC5000-8HC*			Cluster terminal			
	8-channel high speed count module					
MC5000-4HC*	4-channel high speed count module		Cluster terminal			
MC5000-8PO	8-axis 200KHZ pulse output module (1 main module ca	n configure up to 4)	Cluster terminal			
MC5000-2WT*	2-channel weighing module		Plug and pull screw terminal			
MC5000S-ET	EtherCAT expension rack		EtherCAT slave station			
	Accessory					
MCA05-100L	1m terminal line		Tieline			
MCA05-150L	1.5m terminal line		Tieline			



MC 5000 Series High-performance Medium Programming Controller

Power Supply Specification

Power Module	Technical Specification			
Model	MP50AC220			
Dimensions(H×L×W)	100 × 100 × 45 (mm)			
Range of Power Supply	110V~240V			
Input Current	0.7A			
Power Frequency	50/60Hz			

Item	Technical Specification
Dimensions(H×L×W)	100×100×63(mm)
Number of expansion module	16 expansion modules
Speed of Expansion Refresh	7us/IO module
Capacity of Ladder Diagram	320K step
Running Speed	2ms/100K step
Number of Max. Expansion Point	One main module can expand 1024 points/ remote IO 8192 points
SD Card	Yes
USB Download	Yes
Ethernet Download	Yes
RS485	2 channels
Ethernet	7 sockets
	Supporting 6 axis differential output
Differential Output	Pulse+direction, forward/reverse pulse, AB phase
Differential Output	Differential voltage level 5V
	Differential maximum output frequency 2MHz

PO Positioning Module Specification

tem	Technical Specification				
lodel	MC5000-8PO				
sions(H×L×W)	$100 \times 100 \times 34$ (mm)				
speed Input	2 groups encoder (ABZ)				
speed Output	Control 8 axis				
tion Mode of and Output	40 PIN cluster connector				
	Input Channel Specification				
Mode	24V single terminal, 5V difference				
Input Voltage Level	24VDC (-15%~+20%)				
Input Current	5mA (type)				
ON Voltage	>15VDC				
OFF Voltage	< 5VDC				
Filter Time of Port	1ms~64ms(default: 8ms, can be adjusted by programming software				
Input Impedance	e 3.3KΩ				
ial Input Signal	RS422 differential linear drive level based on EIA standard				
Frequency	200kHz (single-channel input)				
Port Mode	Single-point independent common port				
ion Mode	Optical coupling isolution				
tion Display	LED display				
	Output Channel Specification				
Output Control	Pulse+direction, forward/reverse pulse, AB phase				
ut Form	Open-collector				
requency	200KHz				
circuit Voltage	DC5V-24V				
	todel todel sions(H×L×W) speed Input speed Output tion Mode of and Output tion Mode of Input Voltage Level Input Voltage OFF Voltage Filter Time of Port Input Impedance tial Input Signal Frequency Port Mode tion Display Dutput Control ut Form Frequency				

PT Module Specification

Item	Technical Specification									
Model	MC5000-4PT									
Dimensions(H×L×W)	$100 \times 100 \times$	$100 \times 100 \times 34$ (mm)								
Number of Channel	4 channels									
Input Type	Thermal resistance signal: Pt100, Cu100, Cu50									
	Pt100	– 150℃ ~ 600℃	-238° F~1112° F							
Rated Temperature Range	Cu100	– 30°C ~ 120°C	–22° F~248° F							
	Cu50	– 30℃ ~ 120℃	– 22° F~248° F							
Number of AD Bit	16bit									
Conversion Speed	4ms × 4 chann	els (Unused channels	are not converted)							
	Pt100	0.1°C	0.18° F							
Resolution	Cu100	0.1°C	0.18° F							
	Cu50	0.1°C	0.18° F							
Precision	Full range: ±2%									
Isolation	The analog cir the photoelet	rcuit and digital circu ric coupler.	it are separated by							

TC Module Specification

Item	Technical Specification						
Model	MC5000-8TC	MC5000-4TC					
Dimensions(H×L×W)	100×100×34 (mm)						
Number of Channel	8 channels 4 channels						
Input Type	J type, K type, R type, S type, T type, E type, N type, B type thermocouple						
Precision	±0.2% (25℃)						
Precision	±0.4% (0~50°C)						
Number of AD Bit	24bit						
Conversion Speed	100ms/8 channels						
Cold-junction	Internal cold-junction compensation (±0.2 °C)						
Compensation	External cold-junction compensation (±0.1 ℃)						
Resolution	0.1℃						
Isolation Channel to channel isolution The analog circuit and digital circuit are separated by t photoeletric coupler.							

AD Module Specification

Iter	m	Technical Specification		lte	m	Technical Specification	
Mod	el	MC5000-4AD	MC5000-8AD	Mo	del	MC5000-4DA	
Dimension	s(H×L×W)	100×100×34 (mm)		Dimensio	ns(H×L×W)	100×100×34 (mm)	
Number of C	Channel	4 channels	8 channels	Number	of Channel	4 channels	
Range of Quantity		Voltage: -10~+10V(default), Current: 0~20mA, 4~20mA	0~10V, -5~+5V, 0~5V, 1~5V	Range of Analog Quantity Input		Voltage: -10~+10V(default), 0~10V, -5~+5V, 0~5V, 1~5 Current: 0~20mA, 4~20mA	
Number of	Number of AD Bit 16bit		Number of DA Bit		16bit		
Conversion	nversion Speed 8ms/8 channels Conve		Conversi	on Speed	8ms/8 channels		
Number of Average		1~1000		Conversion	Voltage	±0.2% (25°C), ±0.4% (0~55°C)	
Max. measure		±3% of the full	range	precision	Current	±0.2% (25°C), ±0.4% (0~55°C)	
Conversion	Voltage	±0.2% (25°C), ±0.4%	(0~55℃)	Min. laoo	l (voltage)	1kΩ	
precision	Current	±0.2% (25°C), ±0.4%	(0~55℃)	Max. loa	d(current)	500Ω	
Input	Voltage	>250KΩ		Isolati	on	The analog circuit and digital circuit are separated by the photoeletric coupler.	
Impedance	Current	250Ω				· · · · · · · · · · · · · · · · · · ·	
Isolatio	n	The analog circuit and digita the photoeletric coupler.	l circuit are separated by				

IO Module Specification (Screw Terminal& Cluster Terminal)

Model	3200ENN	0032ETN	1616ETN	3232ETN	6400ENN	0064ETN	1600ENN-T	0016ETN-T	0016ERN-T
Dimensions(H×L×W)		100 × 100 × 34 (mm)							
Number of Input Point	32	0	16	32	64	0	16	0	0
Number of Output Point	0	32	16	32	0	64	0	16	16
Wiring Terminal	1 group 40PIN terminal 2 gro				ps 40PIN termina	ıl	Plug and pull screw terminal		
Type of Input Port		Source type / leakage type(SS commom port)							
Voltage of Input Port				>18\	/ ON/<4V OFF	=			
Impedance of Input Port					3.3κ Ω				
Input Filter				1/2/4/8/16/3	2/64 ms (can be	set by software)			
Output Mode	-	Transistor	Transistor	Transistor	-	Transistor	-	Transistor	Relay
Output Circuit-control Voltage	-		24Vdc		-	24Vdc	-	24Vdc	24Vdc/220Vac
Output Circuit-control Current	-		0.3A		-	0.3A	-	0.3A	2A

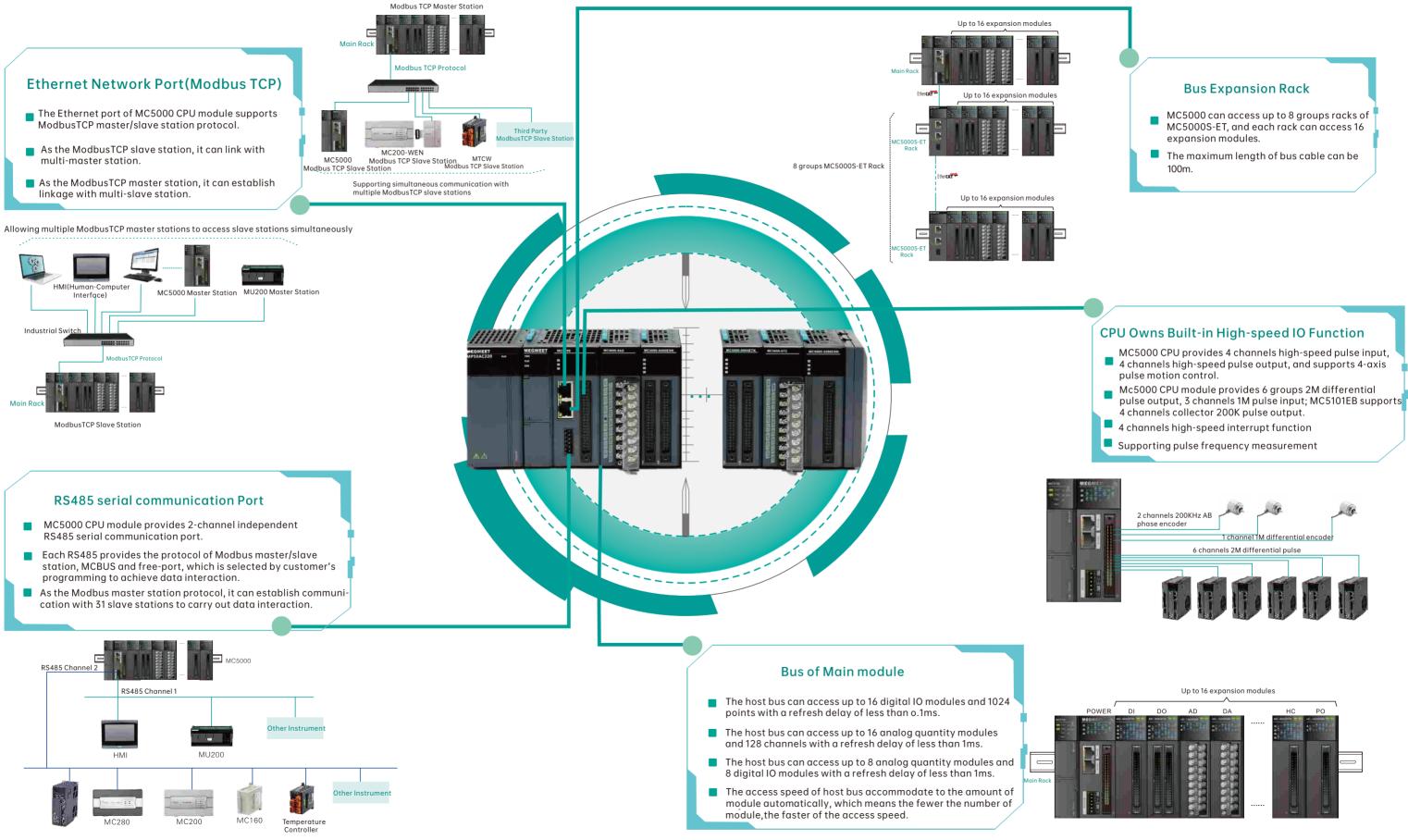
IO Module Specification (Euroblock)

Model	3200ENN-P	0032ETN-P	1616ETN-P	1600ENN-P	0016ETN-P	0016ERN-P				
Dimensions(H×L×W)	100 × 100 × 34 (mm)									
Number of Input Point	32	0	16	16	16	0				
Number of Output Point	0	32	16	0	0	16				
Wiring Terminal		Euroblock								
Type of Input Port		Source type / leakage type(SS commom port)								
Voltage of Input Port			>18V ON	I/<4V OFF						
Impedance of Input Port			3.3	KΩ						
Input Filter			1/2/4/8/16/32/64 ms (o	can be set by software)						
Output Mode	-	Transistor	Transistor	-	Transistor	Relay				
Output Circuit-control Voltage	-	24	Vdc	_	24Vdc	24Vdc/220Vac				
Output Circuit-control Current	-	0.3	3A	-	0.3A	2A				

DA Module Specification

MEGMEET Evervwhere

One-stop Solution



- 4 channels high-speed pulse output, and supports 4-axis



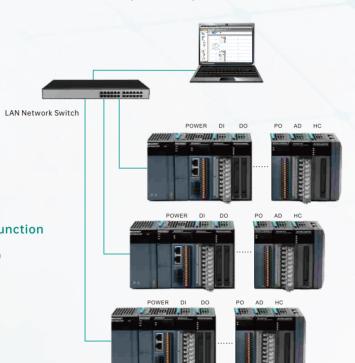
Convenient and Easy-for-use USB Port

The PLC can complete the operation conveniently and easily of programming, downloading, debugging and monitoring through USB port.



Providing Online Debugging and Online Modification Function

- Supporting to set breakpoint individually and single-step running program to reduce time for positioning BUG.*
- Supporting online modification and non-stop debugging function.



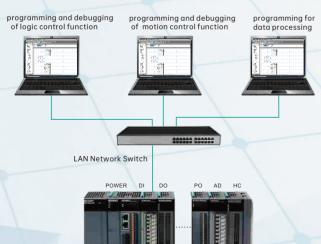
The program and data are both stored on Flash,

which needs not to maintain because of battery-free!

Supporting Multi-person Cooperation to Compile the Program of Complicated Application System

Supporting multi-person programming efficiently and rapidly.

Supporting import and export operations.



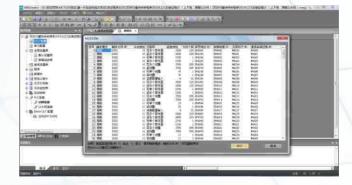
*: Developing



Connecting MC5000 controller through the network to coordinate multi-machine systems handily.

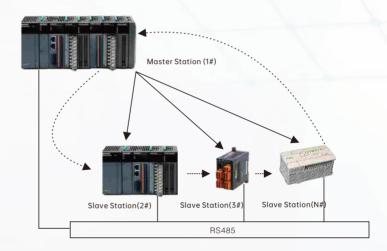


Modbus(RTU/TCP) communication can adopt the method of table configuration to access slave station and simplify programming work.



MCBUS Protocol

The MCBUS builds the loop-token network structure through RS485 and shares data among multiple N:N nodes, where the data of each node is automatically refreshed in real time after finishing configuration.



Rich Accessory

The IO terminals of module are divided into three types:cluster terminal, plug and pull screw terminal, and Euroblock. The user can select appropriate terminal modules according to the industrial site to meet the installation requirements.



Euroblock module Plug and pull screw Cluster terminal module terminal module

MEGMEET 麦格米特控制 15/16

Importing the user program through SD card

Importing the user program through SD card can facilitate the device maintenance.







Line Cluster and Terminal Block

Application Case

Application of MC5100EA in Packaging Machine

The process of packaging machine is composed of five parts: film-feeding, film-cutting, vertical sealing and material-filling, horizontal sealing and independent packaging-dividing. It can carry out 10 rows of packaging operations at the same time and each independent packaging contains two steps of horizontal sealing and vertical sealing.

The control program needs to adopt the electronic CAM motion control algorithm, taking the horizontal sealing lifting as the main axis, the vertical sealing as the slave axis, and keeping the synchronous signal between the horizontal sealing and the vertical sealing to start. The electronic CAM function of MC5100EA can readily complete the synchronous connection among the horizontal seal lifting, vertical sealing and material feeding action, which greatly improves the packaging efficiency.

The control main points of this packaging machine also include film cutting, film deflection-correcting, color mark signal acquisition, temperature control of film packaging, etc. MC5100EA can completely satisfy the needs of complex logic control with its fast response and motion control function.

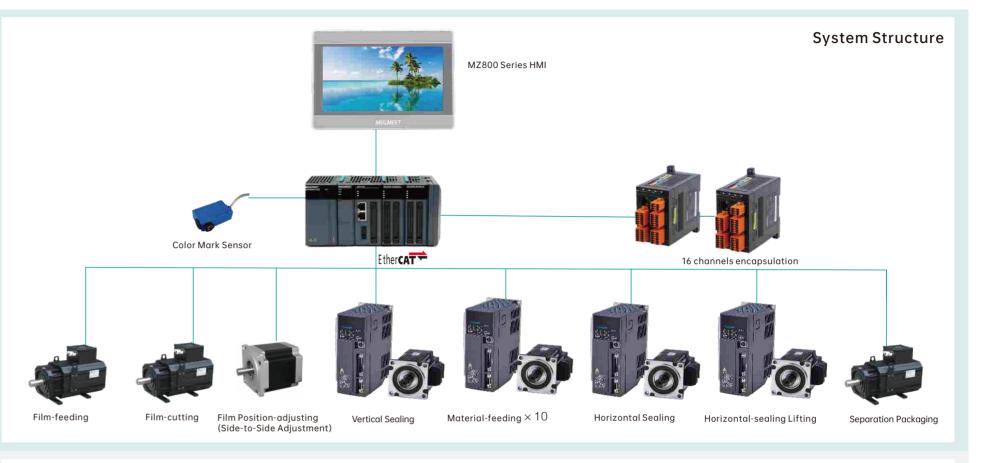
Application of MC5000EB64 in Wire Drawing Machine

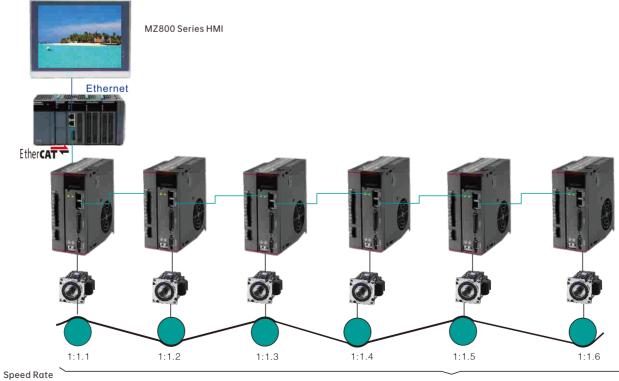
This is a plastic roller-type wire drawing machine, and its process requirements are as follows:

- 64 axis electronic gear, position synchronization
- Synchronous acceleration-deceleration, starting and stopping
- Dynamic adjustment of stretching ratio
- Controlling inter-axis tension to prevent wire breakage

This machine uses MC5000EB64 bus medium PLC as its control core, and controls the synchronous acceleration-deceleration, starting and stopping of the 64 axis though the EtherCAT bus electronic gear, while keeping the tension between the axis constant.

MC5000EB64 can fully meet this systematic requirement that synchronously controls 64 axis and operate at different inter-axis proportional speeds, which are extremely high requirement for the arithmetic speed and performance of controller. The performances of high precision in bus gear linkage control and high difficulty line-breaking can achieve the operation for constant linear winding and unwinding easily.





64 Axis

System Structure

